



SHRI VISHWAKARMA SKILL UNIVERSITY

(A State Skill University, setup by an Act of Legislature in 2016)

Result Notification **B.Voc Robotics and Automation (2023-26)** Semester **Third (Regular)** Examination **December- 2024. (NGF College of Engineering & Technology, Palwal)**

The result of the following candidates who appeared **B.Voc Robotics and Automation (2023-26)** Semester **Third (Regular)** Examination held in **December- 2024 (NGF College of Engineering & Technology, Palwal)** is hereby declared as under:

Sr. No.	Abbreviation	Stand for:
1	Note	Marks show in in the column of result means "Pass"
2	RE	Re-appear in the paper indicated in the result column
3	RL_UMC	Result late due to Unfair Means Case
4	DTN	Detained
5	AB	Absent
6	PC	Paper Cancel

Sr. No.	Nomenclature	
1.	ME-604	Kinematics and Dynamics of robots
2.	ECE-603	Microprocessor and Microcontroller
3.	ECE-602	Electronic Devices and Circuits
4.	EE-601	Automatic Control System
5.	ECE-605	Sensors Applications in Manufacturing
6.	RA-601	Industrial Automation System
7.	ME-605	Hydraulics and Pneumatics
8.	RA-602	Industrial Robotics & Material Handling System
9.	ME-604L	Kinematics and Dynamics of robots
10.	ECE-603L	Microprocessor and Microcontroller
11.	ECE-602L	Electronic Devices and Circuits
12.	EE-601L	Automatic Control System
13.	ECE-605L	Sensors Applications in Manufacturing
14.	RA-601L	Industrial Automation System
15.	ME-605L	Hydraulics and Pneumatics
16.	RA-602L	Industrial Robotics & Material Handling System

S. No.	Regn. No.	Name of Candidate	Result	Detail
1	NGF23URBA101	ADITYA RAJ	RE	RE-ECE-602 RE-EE-601 RE-ECE-605
2	NGF23URBA102	GAJENDER SINGH	RE	RE-ECE-602 RE-EE-601 RE-ECE-605
3	NGF23URBA104	SACHIN KUMAR	RE	RE-ECE-603 RE-ECE-602 RE-EE-601 RE-ECE-605

Dated: 12/03/2024

Examination Department

NGF College of Engineering & Technology, Palwal
Bachelor of Vocation
Robotics and Automation (2023-26)
Third Semester (Regular)- December, 2024

Subject Name			Kinematics and Dynamics of robots			Microprocessor and Microcontroller			Electronic Devices and Circuits			Automatic Control System			Sensors Applications in Manufacturing			Industrial Automation System			Hydraulics and Pneumatics			Industrial Robotics & Material Handling System			Kinematics and Dynamics of robots			Microprocessor and Microcontroller			Electronic Devices and Circuits			Automatic Control System			Sensors Applications in Manufacturing			Industrial Automation System			Hydraulics and Pneumatics			Industrial Robotics & Material Handling System			SGPA		
Subject Code			ME-604			ECE-603			ECE-602			EE-601			ECE-605			RA-601			ME-605			RA-602			ME-604L			ECE-603L			ECE-602L			EE-601L			ECE-605L			RA-601L			ME-605L			RA-602L					
Credit			3			3			3			3			3			3			3			3			1			1			1			1			1			1			1			1					
Maximum Marks			15	35	50	15	35	50	15	35	50	15	35	50	15	35	50	15	35	50	15	35	50	15	35	50	15	35	50	15	35	50	15	35	50	15	35	50	15	35	50	15	35	50	15	35	50						
Minimum Marks			6	14	20	6	14	20	6	14	20	6	14	20	6	14	20	6	14	20	6	14	20	6	14	20	6	14	20	6	14	20	6	14	20	6	14	20	6	14	20	6	14	20	6	14	20						
S. No.			Roll Number		Student's Name		Theory																		Practical																												
							Int.	Ext.	Grade	Int.	Ext.	Grade	Int.	Ext.	Grade	Int.	Ext.	Grade	Int.	Ext.	Grade	Int.	Ext.	Grade	Int.	Ext.	Grade	Int.	Ext.	Grade	Int.	Ext.	Grade	Int.	Ext.	Grade	Int.	Ext.	Grade	Int.	Ext.	Grade											
1	NGF23URBA101	ADITYA RAJ	10	16	C	11	14	C	12	9	F	10	9	F	11	8	F	10	20	B+	10	19	B	10	16	C	31	11	A+	29	12	A+	28	10	A	30	12	A+	31	10	A+	29	11	A+	28	10	A	28	12	A+	RE-ECE-602 RE-EE-601 RE-ECE-605		
2	NGF23URBA102	GAJENDER SINGH	10	19	B	12	14	C	9	10	F	9	9	F	12	9	F	11	18	B	9	16	C	8	20	B	30	12	A+	28	9	A	27	9	A	28	10	A	28	12	A+	30	12	A+	30	9	A	30	10	A+	RE-ECE-602 RE-EE-601 RE-ECE-605		
3	NGF23URBA104	SACHIN KUMAR	8	16	C	9	5	F	10	10	F	12	8	F	10	7	F	9	18	C	11	14	C	10	20	B+	28	10	A	29	8	A	30	12	A+	25	9	B+	29	9	A	27	10	A	28	11	A	30	9	A	RE-ECE-603 RE-ECE-602 RE-EE-601 RE-ECE-605		

Date : 12/3/2025

***The Results displayed here subject to updation/correction. The final result will on DMC.**

Examination Department